Hybrid Hierarchical Multi-Domain Service Function chaining
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Abstract

This document describes a Hybrid Hierarchical Multi-Domain Service Function Chaining (hhSFC) architecture that extends Service Function Chaining (SFC) to multiple domains with different technology, administration or ownership.

The goals of Hybrid Hierarchical SFC are to reduce the complexity of the control plane in a multi-domain scene and make the negotiation between different domains possible.

1. Introduction

Service Function Chaining supports customer traffic passing through an ordered list of functions as required.
The [I-D.ietf-sfc-nsh] creates a service plane via Network Service Headers (NSH), which provide data-plane information to construct service paths and transfer metadata.

The document [I-D.ietf-sfc-control-plane] describes requirements for conveying information between SFC control plane and data plane in a SFC-enabled domain. The document [I-D.dolson-sfc-hierarchical] proposes a hierarchical SFC for multiple domains, which are controlled by a single organization and trusted by each other. Besides, the document only focuses on data plane. [I-D. unify-sfc-control-plane-exp] provides an insight into a Service Function Chain (SFC) control and Network Function Virtualization (NFV) orchestration proof of concept implementation and experimentation in multi-domain/technology environments, which adopts a recursive control plane, but does not consider the business model between different providers to support SFC spanning domains with different ownership.

In this document, we consider SFC traversing different domains owned by different organizations, which means an overarching orchestrator or manager is infeasible.

The Hybrid Hierarchical SFC combines flat distributed control plane and centralized hierarchical control plane. A centralized recursive, hierarchical control plane is recommended to be deployed into a large domain consisting of smaller sub-domains owned by the same organization and a flat distributed control plane is recommended to be deployed into multiple large domains with different ownership.

1.1. Scope

The "domain" discussed in this document is a logical concept. Domain division depends on circumstances including but not limited to: geo-location, technology, administration, or ownership.

This document focuses on control plan. [I-D.dolson-sfc-hierarchical] gives many discussions about data plane, especially internal boundary node (IBN) path configuration, where methods to manipulate NSH are still practicable in this document.

In a recursive hierarchical control plane, an upper level plane is responsible to abstract lower level plane's topologies and services. A mapping element is also needed in every control plane level. The control protocol, abstraction, mapping mechanism and interfaces are out of this document’s scope.
In a flat distributed control plane, horizontal interfaces are used to realize state sharing, context translation and policies negotiation between domains. The protocol is out of this document’s scope.

1.2. Terminology

- **Sub-domains**: Smaller domains in a large administration/physical domain.

- **Multi-Domain Service Function Chaining**: A service function chaining pass through multiple domains.

- **SFC eXchange Platform**: A logical entity that is used for the negotiation between domains. It can be a trusted third-party platform (e.g., deployed in future software defined IXP) or built by a single owner between heterogeneous networks.

- **Abstraction Element (AE)**: A logical entity that abstracts the lower-level topology and services.

- **Mapping Element (ME)**: A logical entity that map upper-level instructions to lower-level control entities.

- **Path Calculation Element (PCE)**: A logical entity that computes service function paths (SFP).

- **Information Base Element (IBE)**: A logical information base entity that stores topology and service information acquired from the abstraction element and provide them to the mapping element and path calculation element.

1.3. Assumptions

Flexible and dynamic SFC is enabled by Software Defined Networking (SDN) and NFV. Distributed NFV crossing different domains makes the hybrid hierarchical control plane necessary.

Network virtualization and network function virtualization create new business models such as service function as a service, a third-party Software Defined IXP (SDX) between ISPs can provides a negotiation platform to support Multi-domain SFC.

In this document, a domain consists of sub-domains and every sub-domain has its own control plane. A single-level control plane is impractical considering the scalability and complexity of control plane.
2. Hybrid Hierarchical Service Function Chaining

2.1. Architecture

Figure 1 shows an example of two-level and two-domain hybrid hierarchical structure. In practice, there could be more levels and domains. In every single domain, each control plane instance manages a single level. Each control plane is agnostic about other levels of hierarchy. Sub-domain control-planes are agnostic about control-planes of other sub-domains. The expectations to control plane in the document [draft-ietf-sfc-hierarchical-02] are satisfied.

```
| +------------+                      | +------------+ |
| |  +   v   <----------------------> |  +   v   |
| v  v  PCE |                      | v  v  PCE |
| AE ME<-- | upper-level          | AE ME<-- |
| +-------+Control Plane       | ^-------+ |
| | | | |
| | | | |
| v  v  PCE |                      | v  v  PCE |
| AE ME<-- |                      | AE ME<-- |
| +-------+               | +-------+ |
| | | | |
| | | | |
| v  v  PCE |                      | v  v  PCE |
| AE ME<-- |                      | AE ME<-- |
```

Figure 1: Architecture

2.2. Control plane

2.2.1. Intra-domain

Several important elements are required in every level control plane. Abstraction Elements abstracts lower-level topology, service and resource. Each level control plane computes service function paths according to the information it acquired. For an upper-level control plane in a domain, the path computation should concern inter-subdomain optimization in a centralized way. For a lower-level control plane, it only cares about the governed sub-domain.
Mapping Elements are responsible to translate the upper-level instructions, which could contain abstracted services requirements, service quality and overlay forwarding behaviors, to the lower-level control instances.

Each level control plane has its own Information Base Elements. Abstraction elements create, update or delete the information in Information Base Elements. The information is utilized by Mapping Elements and Path Calculation Elements.

2.2.2. Inter-domain

Horizontal interfaces should be deployed in the top-level control plane to realize inter-domain communication, including state sharing, context translation and policies negotiation.

Considering the circumstance that domains owned by different ISPs connected by the Internet eXchange Ports, which could be a datacenter implemented SDN technology in the future, an SFC eXchange Platform (SXP) was proposed to support rich business models between different organizations. Their distributed, multi-domain nature makes it possible to enable a highly customized multi-domains SFC.

Figure 2 shows an SFC eXchange Platform connecting three different domains. Figure 3 shows an overview of layered domains and SFC eXchange Platform. In a function as service business model, inter-domain path computation can be driven by service agreements. Horizontal interfaces should be designed between domains and SFC eXchange Platform. Figure 4 shows domains connected by distributed SFC eXchange Platform. SFC eXchange Platforms server as brokers, which orchestrate multi-domains SFC in a distributed way.
Figure 2: Multiple SFC domains connected by a SFC eXchange Platform

Figure 3: Service Function Chaining Exchanging Platform
2.3. Data plane

2.3.1. Intra-domain

The discussion about SFC data plane components in top levels and lower levels in the document [draft-ietf-sfc-hierarchical-02] can be applied in the recursive hierarchical domain defined by this document.

2.3.2. Inter-domain

When packets go out of a domain, the inter-domain NSH should be added. Using unique path is recommended to manipulate inter-domain NSH.

When domains are connected by SDN-enabled SFC eXchange Platforms, which act as SFFs for Multi-domain SFC, the SFC eXchange Platforms will forwarding traffics according to the inter-domain SPI/SI.

3. SFC eXchange Platform

The inter-domain traffic classify rules should be negotiated and decided by administrators of each domain with service agreements and policies. Distributed SFC eXchange Platforms select the service function location from multiple candidate domains.

3.1. Inter-domain negotiation

As a trusted third-party platform, the SFC eXchange platform may not orchestrate the Multi-Domain SFC directly. In other words, it only exchanges and collect domains’ service states and policies. Every domain can decide their own multi-domain SFP according to the states and agreements. The SFC eXchange Platform implements the negotiation results and decisions for domains, such as flow-specific peering. Based on the SFC eXchange Platform, rich business models may appear.
3.2. End-to-end orchestration

In a multi-domain environment, end-to-end visibility could be realized by the exchange platform. One of them (e.g. the one close to customer) can be selected as a manager and takes over the end-to-end management. Exchange platforms communicate with each other and exchange neighboring domains’ quality of service provided. Better domains can be selected from all candidates by the manager. If the performance deteriorates in certain domain, the manager could coordinate with other domains and switch flows to another one. Dynamic and context aware Multi-domain SFC is achievable relaying on the exchange platform.

4. Security Considerations

Authentication mechanism must be applied between intra-domain control plane levels and inter-domain control elements. Lower-level control plane elements must ignore any instructions from authenticated upper-level control plane elements.

5. References

5.1. Normative References


5.2. Informative References


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